



02/29/00

Jc571 U.S. PTO
09/15896

02/29/00

**UTILITY PATENT
APPLICATION TRANSMITTAL**(Only for new nonprovisional applications
under 37 CFR 1.53(b))

Attorney Docket No.

000233

Total Pages

First Named Inventor or Application Identifier

**Akio YONEYAMA, Yasuyuki NAKAJIMA,
Hiromasa YANAGIHARA and Masaru SUGANO**

Express Mail Label No.

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APPLICATION ELEMENTS FOR:

**A VIDEO CODING APPARATUS ACCORDING TO A
FEATURE OF A VIDEO PICTURE**

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10. ☐ English translation Document (if applicable)

11. ☐ Information Disclosure Statement ☐ Copies of IDS Citations

12. ☐ Preliminary Amendment

13. ☒ Return Receipt Postcard (MPEP 503)

14. ☐ Small Entity Statement(s) ☐ Statement filed in prior application
Status still proper and desired.

15. ☒ Claim for Convention Priority ☒ [2] Certified copies of Priority Documents

a. Priority of _____ application no. _____ filed on _____ is claimed under 35 USC 119.

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FEE TRANSMITTAL	Number Filed	Number Extra	Rate	Basic Fee
The filing fee is calculated below				\$690.00
Total Claims	26 - 20	6	x \$18.00	108.00
Independent Claims	5 - 3	2	x \$78.00	156.00
Multiple Dependent Claims			\$260.00	
Basic Filing Fee				954.00
Reduction by 1/2 for small entity				
Fee for recording enclosed Assignment			\$40.00	40.00
TOTAL				\$ 994.00

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18. CORRESPONDENCE ADDRESS

ARMSTRONG, WESTERMAN, HATTORI
McLELAND & NAUGHTON
1725 K Street, N.W. Suite 1000
Washington, D.C. 20006
Telephone: (202) 659-2930
Facsimile: (202) 887-0357

SUBMITTED BY

Typed or Printed Name Mel R. Quintos

Reg. No. 31,898

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A VIDEO CODING APPARATUS
ACCORDING TO A FEATURE OF A VIDEO PICTURE

BACKGROUND OF THE INVENTION

5 Field of the Invention

 The present invention relates to a video coding apparatus and, more particularly, to a video coding apparatus for performing coding by using motion compensatory prediction of a digital video signal.

10 Description of the Related Art

 Among highly efficient coding systems for coding sequentially input video signals in a fewer code quantity, coding systems by the use of the motion and correlation between video pictures of video signals include motion
15 compensatory prediction coding which decodes to reproduce a video picture coded in the past and uses motion information per small block derived from the video picture. One example of the conventional motion compensatory prediction coding is illustrated in Fig. 1.

20 In Fig. 1, when an input video signal 1 of a first screen is input, each of switches is controlled to be connected onto a side (1) by a coding mode control section 12, and the input video signal 1 is input directly into an orthogonal transform unit 3 in order to achieve high coding efficiency.

25 The input video signal 1 is orthogonally transformed by using DCT (discrete cosine transform) or the like in the orthogonal transform unit 3. An orthogonal transform coefficient is

quantized by a quantizer 4. The resultant quantization coefficient is converted into a variable length code such as a Huffman code by a first variable length encoder 5, and then, is input into a video duplexer 15.

5 In the meantime, the quantization coefficient input into an inverse quantizer 6 is inversely quantized, and then, video picture data is restored by an inverse orthogonal transform unit 7. The restored video picture data is stored in a frame memory 9. Moreover, coded data 13 transmitted
10 from the first variable length encoder 5 and quantization information 18 transmitted from the quantizer 4 is duplexed by the video duplexer 15, to be output as a coded video data output 16.

When another input video signal 1 of a next screen is
15 input, each of the switches is controlled to be connected to a contact on a side (2) by the coding mode control section 12, so that the input video signal 1 is input into a predictive signal subtraction section 2 and a motion compensator 10. In the motion compensator 10, a motion vector is detected
20 based on the input video signal 1 and a reference video picture input from the frame memory 9, and then, is input into a position shifter 11 and a second variable length encoder 14. In the second variable length encoder 14, motion vector information is converted into a variable length code such
25 as a Huffman code, thus to be input into the video duplexer 15.

In the position shifter 11, a video signal designated

by the motion vector is extracted from the frame memory 9, and thereafter, is output as a motion compensatory predictive signal to the predictive signal subtraction section 2 and a local decoding addition section 8. In the predictive
5 signal subtraction section 2, the motion compensatory predictive signal is subtracted from the input video signal 1, so that a prediction error thereof is coded. A prediction error signal is orthogonally transformed by using DCT (discrete cosine transform) or the like in the orthogonal
10 transform unit 3 in order to achieve high coding efficiency. The signal quantized by the quantizer 4 is converted into a variable length code such as a Huffman code in the first variable length encoder 5. In order to use the same predictive signal as that on a decoding side, the
15 quantization coefficient obtained by the quantizer 4 is inversely quantized by the inverse quantizer 6, and then, the prediction error signal is locally decoded by the inversely orthogonal transform unit 7. Furthermore, the motion compensatory predictive signal is added with the
20 prediction error signal decoded by the local decoding addition section 8, and then, is stored in the frame memory 9.

In view of convenience of highly efficient coding and decoding reproduction, the video picture is coded by
25 combining three kinds of video coding systems for P, B and I frames.

A minimum unit of video pictures, which are formed by

combining the three kinds of video coding systems and can be decoded independently of each other, is referred to as "a GOP (a Group of Pictures)". The combination of the coding systems is referred to as "a GOP structure". A frame first
5 coded inside one GOP is intra-frame coding (an I frame). Fig. 2 illustrates an example of a GOP. In Fig. 2, the number of frames included in one GOP is referred to as a GOP size, and an interval between P frames or between an I frame and a P frame is referred to as a predictive frame interval.

10 An I frame inserting interval has been conventionally constant irrespectively of the feature of the input video picture: namely, the GOP size has been fixed, so that intra-frame coding has been forcibly carried out per predetermined number of frames. Consequently, the I frame
15 has been inserted even in the case where the input video picture has the high correlation with the reference video picture and coding efficiency can be enhanced by using inter-frame prediction coding.

As for the predictive frame interval, a predictive frame
20 interval of highest coding efficiency depends on the feature of the video picture. For example, a video picture of a swift motion can be predicted from the reference video picture with high efficiency by shortening the predictive frame interval, thus enhancing the coding efficiency. To
25 the contrary, in the case of little variation, the predictive frame interval is prolonged, thereby enhancing the coding efficiency. However, since the predictive frame interval

is fixed to about 0.1 second irrespectively of the feature of the video picture in the conventional system, the coding efficiency can not be enhanced.

Furthermore, in a video picture compression system
5 capable of coding by either a frame structure or a field structure, there can be used either coding by "the field structure" in which one video picture to be coded is coded in a manner corresponding to one field video picture or coding by "the frame structure" in which one video picture to be
10 coded is coded in a manner corresponding to one interlaced frame video picture. However, in the prior art, it is previously designated from the outside as to which is selected out of the frame structure and the field structure before the video picture is coded, so that the video picture
15 to be input is coded by fixedly using the designated structure, thereby outputting coded data. That is, the coding is carried out by the fixed picture structure irrespectively of the feature of the video picture.

Therefore, even in the case of coding a video picture
20 of a swift motion in which the coding efficiency can be enhanced by adopting the field structure, the coding by the frame structure is continued if the frame structure is previously designated as the coding picture structure, resulting in degradation of the coding efficiency. To the
25 contrary, in the case where the coding by the field structure is previously designated, the coding efficiency cannot be enhanced since the field structure is fixedly used even if

the coding efficiency can be enhanced by the frame structure.

Additionally, in the case where it is not found whether the input video picture is an interlaced video picture or a non-interlaced video picture, the high coding efficiency
5 can be achieved by a 2-step system in which it is previously discriminated by some method whether or not the input video picture is an interlaced video picture, and thereafter, the picture structure is switched from the outside at the time of coding based on the discrimination information. Such
10 a 2-step system is unavailable on the assumption of coding at real time.

SUMMARY OF THE INVENTION

The present invention has been accomplished in an
15 attempt to solve the above problems experienced by the prior art. Therefore, an object of the present invention is to provide a video coding apparatus in which coding efficiency can be enhanced and a quality of a coded video picture can be stabilized by adaptively changing a GOP size and a
20 predictive frame interval according to the feature of an input video picture or variations of the feature of the input video picture.

Another object of the present invention is to provide a video coding apparatus in which coding efficiency can be
25 enhanced and a quality of a coded video picture can be stabilized by automatically discriminating whether an input video picture having no information on the feature or

structure of a video picture is an interlaced input video picture or a non-interlaced input video picture and analyzing the feature of the video picture to be input, so as to adaptively change a picture structure in video picture
5 compressing/coding to a frame structure or a field structure.

In order to achieve the above objects, the present invention has a first characteristic in means for detecting a variance between the video pictures based on information on sequentially input video pictures, determining the
10 correlation between the video pictures based on the detected information, and deciding the video picture for which an intra-frame coding system is used according to the degree of the correlation.

With this characteristic, a GOP size depends on the
15 feature of the video picture.

Furthermore, the present invention has a second characteristic in means for detecting a motion feature between the input video pictures so as to decide an optimum predictive frame interval.

20 With this characteristic, the optimum predictive frame interval can be decided based on the motion feature between the input video pictures.

Moreover, the present invention has a third characteristic in means for discriminating whether each of
25 sequentially input video pictures is an interlaced video picture or a non-interlaced video picture, wherein coding by the field structure is selected if the video picture

is an interlaced video picture while coding by the frame structure is selected unless the video picture is an interlaced video picture.

Additionally, the present invention has a fourth
5 characteristic in calculating a variance of a video picture based on an interlaced video picture to be input so as to switch coding by the frame/field structures based on the calculation value.

With these third and fourth characteristics, it is
10 possible to prevent any degradation of the coding efficiency caused by a variation in feature of the input video picture, which was inevitable at the time of fixed selection of the frame/field structures in the prior art. Furthermore, since the discrimination as to whether the input video
15 picture is an interlaced video picture or a non-interlaced video picture, which need be found before the coding, is automatically detected at the time of the coding, the efficient coding can be carried out irrespectively of the feature or structure of the input video picture.

20

BRIEF DESCRIPTION OF THE DRAWINGS

Fig. 1 is a block diagram illustrating a conventional motion compensatory prediction coding apparatus, to which the present invention is applied.

25 Fig. 2 is a view illustrating a conventional GOP structure.

Fig. 3 is a block diagram illustrating a motion

compensatory prediction coding apparatus encompassing the present invention.

Fig. 4 is a block diagram illustrating the configuration of a GOP structure deciding section in a first preferred embodiment according to the present invention.

Figs. 5A and 5B are views explanatory of a method for calculating a variance between two pixels.

Fig. 6 is a view explanatory of creation of a downscaled video picture for the purpose of simple motion estimation.

Fig. 7 is a block diagram illustrating a second preferred embodiment according to the present invention.

Fig. 8 is a block diagram illustrating a third preferred embodiment according to the present invention.

Fig. 9 is a block diagram illustrating a fourth preferred embodiment according to the present invention.

Fig. 10 is a graph illustrating simulation results according to the present invention.

Fig. 11 is a block diagram illustrating the configuration in a fifth preferred embodiment according to the present invention.

Fig. 12 is a view illustrating the configuration of a frame video picture.

Fig. 13 is a view explanatory of a pixel for calculating an absolute difference.

Fig. 14 is a view explanatory of creation of a downscaled feature plane.

Fig. 15 is a view explanatory of processing of the simple

motion estimation.

Fig. 16 is a block diagram illustrating the configuration in a sixth preferred embodiment according to the present invention.

5 Fig. 17 is a block diagram illustrating the configuration in a seventh preferred embodiment according to the present invention.

Fig. 18 is a block diagram illustrating the configuration in an eighth preferred embodiment according
10 to the present invention.

Fig. 19 a block diagram illustrating the configuration in a ninth preferred embodiment according to the present invention.

15 DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENTS

The present invention will be described in detail below in reference to the drawings. Fig. 3 is a block diagram illustrating the configuration in a first preferred embodiment according to the present invention. Although
20 the coding apparatus illustrated in Fig. 1 is used as a video picture coding system in the description below, the present invention is not limited to such a coding apparatus. The same reference numerals as those used in Fig. 1 denote like or corresponding constituent elements.

25 This preferred embodiment is characterized in that the features of sequentially input video signals are analyzed based on the video signals, so that a GOP structure is decided

according to the features, thereby performing coding processing based on the GOP structure.

In Fig. 3, first, the features of sequentially input video signals are analyzed in a GOP structure decision section 20, which then decides a GOP structure according to the input video picture based on the features. Subsequently, when the video picture is coded, a GOP structure information signal 21 is output to a coding mode control section 12; in the meanwhile, coding complexity prediction information 22 is output to a coding bit rate control section 17. Operation other than the above-described operation is similar to that of the coding apparatus illustrated in Fig. 1, and so, its description will be omitted.

Figs. 4, 7, 8 and 9 are block diagrams illustrating preferred processings of the GOP structure decision section 20 illustrated in Fig. 3. First of all, the processing will be explained in reference to Fig. 4 illustrating the first preferred embodiment according to the present invention. First, a frame memory 31 stores therein the sequentially input video signals. The frame memory 31 can store therein video pictures equivalent or more to the maximum GOP size.

An inter-frame variance analysis section 32 calculates a variance of a target video picture based on the video pictures stored in the frame memory 31 and a timewise immediately preceding video picture adjacent to the target video picture, and then, outputs inter-frame variance

information A resulting from the calculation to a GOP
boundary position decision section 33. Here, although the
target video picture and the immediately preceding video
picture are used for the calculation of the inter-frame
5 variance information A, video pictures other than the
immediately preceding video picture may be used.

The GOP boundary position decision section 33 decides
a position optimum for a GOP boundary inside the frame memory
31 based on the inter-frame variance information A output
10 from the inter-frame variance analysis section 32, and then,
outputs the decided position as GOP boundary position
information B. Upon this decision of the GOP boundary
position, the video pictures prior to the decided GOP
boundary position stored inside the frame memory 31
15 constitute one GOP.

A simple motion estimation section 34 decides a
reference video picture out of the video pictures equivalent
to one GOP size stored in the frame memory 31 after an I
frame inserting position, i.e., after the decision of the
20 size of one GOP by the GOP boundary position decision section
33, and then, outputs motion feature prediction information
C by simple motion estimation between the reference video
picture and the other video picture.

Subsequently, a predictive frame interval decision
25 section 35 decides a predictive frame interval based on the
motion feature prediction information C input from the simple
motion estimation section 34, and then, outputs predictive

frame interval information D.

The inter-frame variance information A, the GOP boundary position information B, the motion feature prediction information C and the predictive frame interval
5 information D are input into a coding complexity prediction section 37, which predicts coding complexity at each of I, P and B frame coding modes so as to output the resultant information as coding complexity prediction information E to a coding bit rate control section 17.

10 The coding bit rate control section 17 controls a coding bit rate in coding the input video picture in consideration of the coding complexity prediction information E input from the coding complexity prediction section 37. The GOP boundary position information B and the predictive frame
15 interval information D are output also to a coding mode control section 12, which controls switches at the time of the coding in the GOP structure decided on the basis of the information B and D.

After the decision of the structure of one GOP inside
20 the frame memory 31, the frame memory 31 outputs a video signal to the predictive signal subtraction section 2 shown in Fig. 3 in order to code each video picture of the GOP. Information on the output video signal is erased from the frame memory 31.

25 Upon completion of the coding of one GOP, the frame memory 31 stores therein video pictures input in sequence posterior to the residual video pictures stored therein.

When the frame memory 31 stores therein the video signals equivalent to the GOP size to the maximum, it performs the processing of deciding a next GOP structure. This processing is repeated.

5 Next, description will be given in detail of the operation of each of the constituent elements illustrated in Fig. 4.

First, the frame memory 31 stores therein the sequentially input video signals. The number of video
10 pictures to be stored is equivalent or more to the maximum GOP size which is decided at the time of the coding. The frame memory 31 outputs the video signals to the inter-frame variance analysis section 32 and the simple motion estimation section 34, respectively. When the structure of one GOP
15 is decided in the stored video pictures, the video signal is output to the video coding apparatus. Consequently, the output video signal is erased from the frame memory 31, and then, a newly input video signal is stored in that vacant region in the frame memory 31.

20 Subsequently, the inter-frame variance analysis section 32 fetches two pieces of video picture information from the frame memory 31, to calculate the inter-frame variance information A. The calculating methods include a method for calculating a variance based on the intra-frame
25 sum of absolute differences of pixel information on the two video pictures at the same position; and a method for dividing the video picture into small blocks, determining dispersion

values of pixels in the small blocks, and calculating the intra-frame sum of absolute differences between frames in which the dispersion values are representative of the small blocks.

5 In the former deciding method, as shown in, for example, Fig. 5A, assuming that pixel values of the video pictures (i) and (j) are designated by $P_{i1}, P_{i2}, \dots, P_{in}$ and $P_{j1}, P_{j2}, \dots, P_{jn}$, respectively, the intra-frame sum A of the absolute differences is expressed by the following equation

10 (1):

$$A = \sum_{k=1}^n |P_{ik} - P_{jk}| \quad \dots (1)$$

Furthermore, in the latter deciding method, as shown in, for example, Fig. 5B, assuming that dispersion values of the small blocks in the video pictures (i) and (j) are designated by $\sigma_{i1}, \sigma_{i2}, \dots, \sigma_{im}$ and $\sigma_{j1}, \sigma_{j2}, \dots, \sigma_{jm}$, respectively, the intra-frame sum A of the absolute differences is expressed by the following equation (2):

15

$$A = \sum_{k=1}^m |\sigma_{ik} - \sigma_{jk}| \quad \dots (2)$$

Although each of the pixel values in the decision methods is processed by using only luminance, it may be processed by using chrominance or using both luminance and chrominance. The inter-frame variance information A calculated by the inter-frame variance analysis section 32 is output to the GOP boundary position decision section 33 and the coding complexity prediction section 37.

20

25

The GOP boundary position decision section 33 decides a video picture immediately before the frame as the GOP

boundary based on the inter-frame variance information A
input from the inter-frame variance analysis section 32 in
the case where the value of the information A exceeds a
predetermined threshold value. Otherwise, the GOP boundary
5 position decision section 33 may decide a video picture
immediately before a video picture having a maximum value
of the information A as the GOP boundary based on the
inter-frame variance information A on all of the video
pictures stored inside the frame memory 31; or it may decide
10 it based on a logical sum or a logical product obtained by
both the system using the threshold value and the system
using the maximum value. The GOP boundary position
information B obtained in the GOP boundary position decision
section 33 is output to the simple motion estimation section
15 34, the coding mode control section 12 and the coding
complexity prediction section 37.

After one GOP size with respect to the video pictures
inside the frame memory 31 is decided in the GOP boundary
position decision section 33, the simple motion estimation
20 section 34 performs simple motion estimation processing in
order to predict motion information on the video picture
inside the GOP. In a method for collecting most accurate
motion information, the input video picture is divided into
small blocks each composed of 8x8 pixels or 16x16 pixels,
25 each of the small blocks is subjected to motion estimation,
and consequently, the most accurate motion information is
determined based on the resultant motion information on each

of the small blocks in the same manner as the motion estimation processing by the motion compensator 10 in the video coding apparatus for the video pictures illustrated in Fig. 3. However, since a processing quantity required for the motion estimation is huge, addition processing of 2^{31} times or more is required for the motion estimation processing of one video picture in the case where, for example, the video picture size is 720 x 480 pixels and the motion estimation falls within the range of ± 16 pixels. As a consequence, the present invention uses the means for predicting the motion information on the video picture based on the information resulting from the simple motion estimation processing of a small processing quantity performed in the simple motion estimation section 34. Description will be given below of the simple motion estimation processing.

First, one video picture decided inside the GOP is selected as a reference video picture. Thereafter, the reference video picture is divided into small blocks. Subsequently, a downscaled video picture, in which the small block is expressed by one representative value, is created. Here, the dispersion of all of the pixel values inside the small block, for example, can be used for calculation of the representative value. The oldest video picture out of the target GOP is selected as the reference video picture, but other video pictures may be selected.

Next, in order to grasp the motion features in comparison with the reference video picture, the target video

pictures are determined, and then, the downscaled video pictures of these video pictures are created. Thereafter, the motion estimation processing is performed by the use of the downscaled video pictures of both of the reference video picture and the target video picture. Although according to the present invention, the motion estimation processing is performed with respect to all of the video pictures except the reference video picture inside the GOP, not all of the video pictures but some selected video pictures may be subjected to the motion estimation processing.

Fig. 6 illustrates a method for creating the downscaled video picture. Assuming that a video picture to be input is composed of M pixels in a horizontal direction multiplied by N pixels in a vertical direction and a small block is composed of 8 pixels in the horizontal and vertical directions, respectively, a representative value of the small block is one with respect to 64 pixels, so that a downscaled video picture to be created is composed of $M/8$ in the horizontal direction multiplied by $N/8$ in the vertical direction in the case where N and M each are a multiple of 8. Furthermore, the size of the small block may be processed not in the size of 8×8 pixels, but in the size of 16×16 pixels or in the sizes of all other rectangular blocks.

Although the dispersion value of each of the pixel values inside the small block is used for the calculation of the representative value per small block in this system, an average value, a standard deviation, an absolute error

sum with respect to the average value or combinations thereof may be used. Although a luminance is used herein as the pixel value, a luminance and/or a chrominance may be used.

The motion estimation is generally performed per small
5 block, so that a vector indicating a position of a smallest difference is calculated, thereby obtaining the motion feature. However, accuracy of the motion vector information is low since the downscaled video picture is used in this system. Consequently, the smallest motion
10 compensatory prediction error at the time of the motion estimation based on the downscaled video picture information is a motion feature value of the video picture, i.e., the motion feature prediction information C as an index of the magnitude of the motion of the entire video picture. As square
15 error, an absolute error, an absolute error at a square root may be used for the calculation of the motion compensatory prediction error.

The obtained motion compensatory prediction error as the motion feature prediction information C is input into
20 the predictive frame interval decision section 35, which decides a predictive frame interval based on the motion feature prediction information C. The predictive frame interval is small in the case where a motion or a variation between the video pictures is great in coding the video
25 pictures; to the contrary, the predictive frame interval is large in the case where a motion or a variation between the video pictures is small in coding the video pictures,

thereby achieving most efficient coding. Consequently, in order to grasp the motion feature over one GOP, the motion feature prediction information C on all of the reference video picture and other video pictures inside one GOP is
5 obtained, and then, the average value thereof is obtained. The average value is used as a representative value, on the basis of which the predictive frame interval is determined. One of the characteristics of the present invention resides in that the inversely proportional relationship is
10 established between the predictive frame interval and the obtained average value. Besides the method for using the average value, a maximum value or a minimum value may be used for the calculation of the representative value inside one GOP.

15 Since a relative motion quantity with respect to a pixel becomes large in the case where the resolution of the video picture to be input is high, the inversely proportional relationship is established between the resolution of the video picture and an optimum predictive frame interval.
20 Another characteristic of the present invention resides in that the inversely proportional relationship with respect to the resolution information on the video picture is considered in deciding the predictive frame interval. The decided predictive frame interval information D is output
25 to the coding complexity prediction section 37 and the coding mode control section 12. The GOP boundary position information B and the predictive frame interval information

D are transmitted together to the coding mode control section 12, in which the switches are controlled based on the information B and D in coding the video pictures.

The inter-frame variance information A, the GOP
5 boundary position information B, the motion feature prediction information C and the predictive frame interval information D are input into the coding complexity prediction section 37, which calculates coding complexity prediction information E as an index of generated code quantity
10 prediction in coding at a coding mode of each of the I, P and B frames, and then, outputs the coding complexity prediction information E to the coding bit rate control section 17.

When the processing proceeds to coding of a new GOP,
15 the coding bit rate control section 17 renews coding complexity prediction information at each of the coding modes based on the coding complexity prediction information E input from the coding complexity prediction section 37. Coding complexity prediction information used at past frames having
20 the same coding mode has been conventionally used irrespectively of switching of the input video picture or fluctuations. Consequently, in the case where an input video picture has suffered from a large change such as a change in scene, the video picture has been influenced by
25 coding complexity prediction information on a frame having no correlation, with an attendant problem of markedly degradation of a quality of the video picture. However,

since the prediction is carried out based on the information of the video picture to be coded according to the present invention, the above-described problem can be solved.

Subsequently, explanation will be made on a method for
5 calculating the coding complexity prediction information E at each of the coding modes. A video picture which is coded as an I frame is divided into small blocks and the dispersion of a pixel value per small block is decided, so that the coding complexity prediction information E at the
10 I frame is calculated by a product of an intra-frame average of the dispersions multiplied by a fixed value SI as a scaling parameter. Luminance information and/or chrominance information may be used as the pixel value.

In the case where an absolute difference calculated
15 between the dispersion of the pixel value per small block and dispersion of a pixel value of an adjacent small block exceeds a threshold value, it is judged that the small block region of the input video picture includes edge information such as an outline, so that the coding bit rate control section
20 17 takes the judgement into consideration so as to assign many coding quantities in coding the small block region.

An average of the motion compensatory prediction errors is obtained based on all of the motion feature prediction information C inside the target GOP, and then, the coding
25 complexity prediction information E at the P frame is calculated by a product of the average value multiplied by a fixed value SP as a scaling parameter. Otherwise, the

coding complexity prediction information E at the I frame may be scaled for the calculation.

The coding complexity prediction information E at the B frame is calculated by a product of the coding complexity prediction information at the P frame multiplied by a fixed value SB as a scaling parameter.

Subsequently, a second embodiment according to the present invention is illustrated in Fig. 7. The present embodiment is configured such that the processing of the coding complexity prediction section 37 in the first embodiment illustrated in Fig. 4 is omitted.

Next, a third embodiment according to the present invention is illustrated in Fig. 8. The present embodiment is configured such that the processing concerned in the decision of the GOP size in the second embodiment illustrated in Fig. 7 is omitted. In the present embodiment, a GOP size is fixed with a length designated in advance. In each GOP, an optimum predictive frame interval is adaptively varied based on motion feature prediction information C.

Subsequently, a fourth embodiment according to the present invention is illustrated in Fig. 9. The present embodiment is configured such that the processing concerned in the decision of the predictive frame interval in the second embodiment illustrated in Fig. 7 is omitted. In the present embodiment, the predictive frame interval is fixedly designated in advance. Only a GOP size is adaptively varied based on inter-frame variance information A which is a

feature of an input video picture.

As is obvious from the above description, since according to the present invention the GOP size is decided according to the feature or variation of the input video picture, the GOP size can be decided in a manner adaptive
5 to the variation of the input video picture. Therefore, it is possible to avoid degradation of the coding efficiency or fluctuation of a quality of the video picture which may occur in the case of coding with the fixed GOP size.

Moreover, since the motion feature of the video picture inside the GOP can be detected based on the decided GOP size and the predictive frame interval according to the motion feature can be set, the predictive frame interval can be taken according to the motion feature of the input video
15 picture. Consequently, it is possible to enhance the coding efficiency more than the case of the conventional coding at the fixed predictive frame interval.

Additionally, the coding complexity prediction information used in the preceding GOP has been considered
20 even in the case where there has been no correlation in video picture feature between a preceding GOP and a target GOP due to a scene change or the like in the prior art, thereby inducing markedly fluctuations or deterioration of a quality of the video picture to be coded or degradation of the coding
25 efficiency. In contrast, according to the present invention, the coding complexity prediction information is calculated based on the features of the video pictures inside

the target GOP after the completion of the coding of one
GOP and before coding of a next GOP, so that a video picture
can be coded with a stable quality without any influence
of the feature of the video picture inside an irrelevant
5 GOP.

Fig. 10 shows the simulation result on a video picture
with a change in scene in the MPEG2 system. In this
simulation, under the condition where compression coding
was carried out at a coding rate of 4 Mbit/s, fluctuation
10 of PSNR was small and the quality of the video picture could
be improved by 0.65 dB according to the present invention
in comparison with the coding in the prior art in which the
GOP size was fixed to 15 frames and the predictive frame
interval was fixed to 3 frames.

15 Next, a fifth embodiment according to the present
invention will be explained in reference to Fig. 11. In
the present embodiment, it is discriminated based on each
of sequentially input video signals (stationary video
signals) whether or not an input video picture is an
20 interlaced video picture. If the input video picture is
an interlaced video picture, a downscaled feature plane is
created, and then, coding in a frame/field structure is
decided based on the result of simple motion estimation
processing by the use of the downscaled feature plane.

25 In Fig. 11, an interlaced/non-interlaced video
discriminant section 51 discriminates whether each of
sequentially input video signals 1 is an interlaced video

signal or a non-interlaced video signal. The discrimination result is output as interlaced/non-interlaced discriminant information 52 to a downscaled feature plane creation section 53. The
5 downscaled feature plane creation section 53 creates downscaled feature plane information 54 in consideration of the feature of the video picture with respect to the video picture which is discriminated as the interlaced video picture in the interlaced/non-interlaced video
10 discriminant section 51, and outputs the downscaled feature plane information 54 to a simple motion estimation section 55. The simple motion estimation section 55 performs simple motion estimation processing between two downscaled feature planes, and outputs the resultant motion compensatory
15 prediction error as image variance information 56 to a frame/field structure decision section 57.

Based on the image variance information 56 obtained by the simple motion estimation section 55, the frame/field structure decision section 57 decides coding by the frame
20 structure in the case of a small variance while coding by the field structure in the case of a large variance, and outputs the result as picture structure information 58 to a video coding section 59. The video coding section 59 performs video coding with respect to the input video signal
25 1 in response to picture structure information 58 indicated by the frame/field structure decision section 57, and outputs coded data 16. Here, the video coding section 59 switches

the operations of, for example, the motion compensator 10, the first variable length encoder 5 and the second variable length encoder 14, illustrated in Fig. 1, to the operation adaptive to coding in the frame/field structure according to the designation of the frame/field structure based on the picture structure information 58.

Next, description will be given of one example of the configuration and operation of each of the constituent elements in Fig. 11. First, explanation will be made on the interlaced/non-interlaced video discriminant section 51. The discrimination as to whether or not the video picture is an interlaced video picture is decided by the calculation with some adjacent pixels based on the video picture information to be input. Fig. 12 illustrates the configuration of frame video information to be input. The video information is composed of the array of spacewise uniformly arranged pixels. Based on the video information, five pixel values continuous in a vertical direction at an arbitrary position are taken, and then, an absolute difference between two pixels is calculated, as illustrated in Fig. 13.

There are calculated absolute differences between pixels belonging to the same fields of 0 and -2, 0 and 2, and -1 and 1 in five pixels $p(-2)$ to $p(2)$, wherein a pixel positioned at the center in the vertical direction is designated by $p(0)$, and absolute differences between pixels belonging to different fields of 0 and -1, and 0 and 1. It

is verified whether or not the condition expressed by inequality (3) below is satisfied:

$$\text{Max}(d(0,-2),d(0,2),d(-1,1)) < \text{threshold value} \dots (3)$$

Subsequently, if the condition expressed by inequality
5 (3) above is satisfied, it is further verified whether or not the condition expressed by inequality (4) below is satisfied:

$$(\text{Max}(d(0,-2),d(0,2),d(-1,1))+\text{offset}) < \text{Min}(d(0,-1),d(0,1)) \dots (4)$$

10 Here, $d(a,b)$ represents an absolute difference between a and b ; $\text{Max}(a,b,c)$, a maximum value of a , b and c ; and $\text{Min}(a,b,c)$, a minimum value of a , b and c . That is, in the case where the pixel values belonging to the same field are similar to each other and the maximum absolute difference
15 is less than the threshold value (a fixed value), it is verified whether or not the minimum value of the absolute differences at the different fields exceeds a value obtained by adding an offset (a fixed value) to the maximum absolute difference at the same field. This processing is performed
20 with respect to all of the pixels or the arbitrary number of positions inside the video picture. In the case where the points satisfying inequalities (3) and (4) exceed a predetermined rate of the points satisfying inequality (3), the video picture is discriminated as an interlaced video
25 picture, and then, the result is output as the interlaced/non-interlaced discriminant information 52 per frame to the downscaled feature plane creation section 53.

Furthermore, although the description has been given of the example in which the discrimination of the interlaced/non-interlaced video picture is performed by the use of the five pixels in the vertical direction, the number of pixels required for the verification is arbitrary as long as it is three or more wherein comparison can be conducted between adjacent pixels at the same field and pixels at different fields. Moreover, the position of the pixel to be verified may be any of all of the pixels inside the video picture. Otherwise, a sample point may be investigated such that the above-described verification is conducted at a specific position or an arbitrary position inside one block composed of, for example, five pixels in the vertical direction and n pixels in the horizontal direction. Alternatively, utterly arbitrary points may be spot-checked at random.

Subsequently, explanation will be made on the processing of the downscaled feature plane creation section 53 illustrated in Fig. 11, i.e., the processing of creating a downscaled plane in consideration of the feature of the video picture based on an original video picture in reference to Fig. 14. First, the original video picture is divided into small blocks, each of which is expressed by a representative value. According to the present invention, the standard deviation of the pixel values per small block is used as the representative value. An average value or a median value may be used as the representative value. A

luminance component of the pixel may be used as the pixel value at the time of the calculation; or, other components or an average thereof may be used. Furthermore, the size of the small block may be arbitrarily set. Assuming that
5 the small block is composed of p_h pixels in the horizontal direction multiplied by p_v pixels in the vertical direction, the downscaled feature plane is composed of H/p_h pixels in the horizontal direction multiplied by V/p_v pixels in the vertical direction with respect to the size of the original
10 video picture (H pixels in the horizontal direction multiplied by V pixels in the vertical direction), so that the number of samples becomes $1/(p_h \times p_v)$ with respect to the number of pixels of the original video picture. The downscaled plane having the standard deviation of the small
15 block as the representative value is the downscaled feature plane information 54.

Next, description will be given below of the processing by the simple motion estimation section 55 illustrated in Fig. 11. The simple motion estimation section 55 performs
20 the motion estimation processing between the two downscaled feature planes based on the downscaled feature plane information 54 created by the downscaled feature plane creation section 53. A timewise distance between a reference plane and a target plane to be subjected to the
25 simple motion estimation is an arbitrarily fixed value. Motion estimation by block matching or the like can be used in the motion estimating method. In this case, the block

can take an arbitrary natural number for both of horizontal and vertical sizes on the downscaled feature plane. Consequently, the motion estimation per block can be carried out by using, as one block, one sample at the minimum or
 5 the entirety of one downscaled feature plane at the maximum.

Referring to Fig. 15, explanation will be made below. An upper left coordinate of the set block is designated by (k,l) ; an element on a downscaled feature plane 1, $c(k,l)$; and an element on a downscaled feature plane 2, $r(k,l)$.
 10 Reference character N represents the size of the block in the horizontal direction; and M, the size of the block in the vertical direction. The estimation range falls within $\pm sh$ in the horizontal direction and $\pm sv$ in the vertical direction. An average motion compensatory prediction error
 15 $E(k,l)$ of one element in this simple motion estimation is determined based on the minimum error within the estimation range according to the following equations (5) and (6):

$$E(k,l) = \text{Min}(\text{Err}(k,l,h,v)) \quad \dots (5)$$

here,

$$20 \quad \text{Err}(k,l,h,v) = \sum_{m=0}^{M-1} \sum_{n=0}^{N-1} |c(k+m,l+n) - r((k+m+h), (l+n+v))| \quad \dots (6)$$

$$(-sh \leq h \leq sh, -sv \leq v \leq sv)$$

As to the prediction error $E(k,l)$, square root
 25 processing may be performed after determination of a square error, or an absolute difference may be used. The prediction error $E(k,l)$ obtained by the simple motion estimation

processing is determined with respect to all of the blocks on the downscaled feature plane 1, thereby obtaining the sum Esum on the downscaled feature plane 1. The sum Esum is an index indicating the magnitude of a variation between
5 two video pictures. The sum Esum as the image variance information 56 is output to the frame/field structure decision section 57.

Next, the frame/field structure decision section 57 illustrated in Fig. 11 judges whether or not the image
10 variance information 56 per input frame exceeds a threshold value. If the image variance information 56 per input frame is the threshold value or more, the frame/field structure decision section 57 decides the field structure; to the contrary, if the image variance information 56 per input
15 frame is less than the threshold value, the frame/field structure decision section 57 decides the frame structure. Thereafter, the frame/field structure decision section 57 outputs the decision result as the picture structure information 58 to the video coding section 59.

20 The video coding section 59 illustrated in Fig. 11 performs the compression coding of the video signal to be input by the use of the picture structure designated by the picture structure information 58 output from the frame/field structure decision section 57, and then, outputs the coded
25 data 16. Specifically, the video coding section 59 switches, for example, the operations of the motion compensator 10, the first variable length encoder 5 and the second variable

length encoder 14 illustrated in Fig. 1 to the system adaptive to coding in the frame/field structure according to the picture structure.

Fig. 16 is a block diagram illustrating the configuration of a sixth embodiment according to the present invention. The same reference numerals as those in Fig. 11 designate like or corresponding constituent elements. In the present embodiment, a video coding apparatus comprises a downscaled feature plane creation section 53, a simple motion estimation section 55 and a frame/field structure decision section 57. The present embodiment is characterized in that the frame/field structure decision section 57 selects coding by a field structure if image variance information 56 obtained by simple motion estimation processing in the simple motion estimation section 55 exceeds a certain threshold value; in the meantime, it selects coding by a frame structure if the image variance information 56 is less than the threshold value. There is a difference between the fifth embodiment illustrated in Fig. 11 and the present embodiment in that in the former embodiment the downscaled feature plane creation section 53 creates the downscaled feature plane in the case of the interlaced video picture, while in the latter the downscaled feature plane creation section 53 creates the downscaled feature plane also in the case of a non-interlaced video picture.

Fig. 17 is a block diagram illustrating the configuration of a seventh embodiment according to the

present invention. The same reference numerals as those in Fig. 11 designate like or corresponding constituent elements. In the present embodiment, a video coding apparatus comprises an interlaced/non-interlaced video discriminant section 51 and a frame/field structure decision section 57. The interlaced/non-interlaced video discriminant section 51 discriminates whether or not an input video picture is an interlaced video picture. The present embodiment is characterized in that the frame/field structure decision section 57 selects coding by a field structure in the case where the input video picture is an interlaced video picture; to the contrary, it selects coding by a frame structure in the case where the input video picture is a non-interlaced video picture.

Fig. 18 is a block diagram illustrating the configuration of an eighth embodiment according to the present invention. The same reference numerals as those in Fig. 11 designate like or corresponding constituent elements. In the present embodiment, a video coding apparatus comprises an interlaced/non-interlaced video discriminant section 51, an interlaced/non-interlaced video switch section 60, a downsampled feature plane creation section 53, a simple motion estimation section 55 and a frame/field structure decision section 57. The interlaced/non-interlaced video discriminant section 51 discriminates whether one video picture input first or a plurality of video pictures are interlaced or non-interlaced

video pictures. Based on the discrimination, the interlaced/non-interlaced switch section 60 switches "0" and "1". As for video pictures input hereafter, the interlaced/non-interlaced video discriminant section 51
5 does not perform discrimination of interlaced or non-interlaced video pictures. The present embodiment is different in the above-described point from the fifth embodiment illustrated in Fig. 11.

Fig. 19 is a block diagram illustrating the
10 configuration of a ninth embodiment according to the present invention. The same reference numerals as those in Fig. 11 designate like or corresponding constituent elements. In the present embodiment, a video coding apparatus comprises an interlaced/non-interlaced video discriminant section 51,
15 an interlaced/non-interlaced video switch section 60 and a frame/field structure decision section 57. The interlaced/non-interlaced video discriminant section 51 discriminates whether one video picture input first or a plurality of video pictures are interlaced or non-interlaced
20 video pictures. Based on the discrimination, the interlaced/non-interlaced switch section 60 switches "0" and "1". As for video pictures input hereafter, the interlaced/non-interlaced video discriminant section 51 does not perform discrimination of interlaced or
25 non-interlaced video pictures. The present embodiment is different in the above-described point from the seventh embodiment illustrated in Fig. 17.

As is obvious from the above description, although the video picture having an improvable coding efficiency is limited in the conventional coding by the fixed picture structure, since the coding is selected dependently on the picture structure according to the feature or variation of the input video picture according to the present invention, the high coding efficiency can be kept even if a video picture having any feature is input or the feature of the video picture is varied on the way.

Furthermore, the video coding simulation is conducted by using the MPEG2 video coding system as the video coding system in which the motion compensatory prediction coding can be carried out by either the frame structure or the field structure. As a result, the quality of the video picture can be improved by about 0.4 dB to 1.0 dB of PSNR according to the present invention in comparison with the case of the fixation in the frame structure under the condition of the compression coding at a coding rate of 4 Mbit/s.

WHAT IS CLAIMED IS:

1. A video coding apparatus for coding a video picture
by the use of motion compensatory prediction of each of video
pictures with respect to sequentially input video signals,
5 the video coding apparatus comprising:

inter-frame variance calculation means for
calculating a variance between timewise adjacent input video
signals with respect to the input video signals; and

intra-frame coding mode decision means for deciding
10 an intra-frame coding mode without using any motion
compensatory prediction based on the variance, a GOP boundary
position being decided based on the decision by the
intra-frame coding mode decision means.

2. A video coding apparatus for coding a video picture
15 by the use of motion compensatory prediction of each of video
pictures with respect to sequentially input video signals,
the video coding apparatus comprising:

one-way coding (P) frame interval decision means for
deciding a P frame interval for carrying out motion
20 compensatory prediction coding based on the features of the
input video pictures, the P frame interval inside a GOP being
decided based on the decision by the P frame interval decision
means.

3. A video coding apparatus for coding a video picture
25 by the use of motion compensatory prediction of each of video
pictures with respect to sequentially input video signals,
the video coding apparatus comprising:

inter-frame variance calculation means for calculating a variance between timewise adjacent input video signals with respect to the input video signals;

intra-frame coding mode decision means for deciding
5 an intra-frame coding mode without using any motion compensatory prediction based on the variance; and

one-way coding (P) frame interval decision means for deciding a P frame interval for carrying out motion compensatory prediction coding based on the features of the
10 input video pictures,

a GOP boundary position being decided based on the decision by the intra-frame coding mode decision means, and the P frame interval inside a GOP being decided based on the decision by the P frame interval decision means.

15 4. A video coding apparatus according to claim 1, wherein the intra-frame coding mode decision means selects an intra-frame coding mode when the inter-frame variance exceeds a predetermined threshold value.

5. A video coding apparatus according to claim 3,
20 wherein the intra-frame coding mode decision means selects an intra-frame coding mode when the inter-frame variance exceeds a predetermined threshold value.

6. A video coding apparatus according to claim 1, wherein the inter-frame variance is calculated by using at
25 least one of an absolute difference between the input video pictures and a pixel dispersion value of each of small blocks, into which the input video picture is divided.

7. A video coding apparatus according to claim 3,
wherein the inter-frame variance is calculated by using at
least one of an absolute difference between the input video
pictures and a pixel dispersion value of each of small blocks,
5 into which the input video picture is divided.

8. A video coding apparatus according to claim 2,
wherein the P frame interval decision means divides the input
video picture into small blocks and carries out simple motion
compensatory prediction by the use of a representative value
10 per small block so as to decide the P frame interval.

9. A video coding apparatus according to claim 3,
wherein the P frame interval decision means divides the input
video picture into small blocks and carries out simple motion
compensatory prediction by the use of a representative value
15 per small block so as to decide the P frame interval.

10. A video coding apparatus according to claim 8,
wherein the representative value uses either one of an
average inside the small block and a dispersion value inside
the small block.

20 11. A video coding apparatus according to claim 9,
wherein the representative value uses either one of an
average inside the small block and a dispersion value inside
the small block.

12. A video coding apparatus according to claim 2,
25 wherein the P frame interval decision means controls to make
the frame interval small in the case where a motion
compensatory prediction error is large while controls to

make the frame interval great in the case where the motion compensatory prediction error is small.

13. A video coding apparatus according to claim 3, wherein the P frame interval decision means controls to make
5 the frame interval small in the case where a motion compensatory prediction error is large while controls to make the frame interval great in the case where the motion compensatory prediction error is small.

14. A video coding apparatus according to claim 2,
10 further comprising means for dividing a target video picture into small blocks so as to judge an edge region inside the video picture based on the dispersion value of pixel information on the small block.

15. A video coding apparatus according to claim 3,
15 further comprising means for dividing a target video picture into small blocks so as to judge an edge region inside the video picture based on the dispersion value of pixel information on the small block.

16. A video coding apparatus according to claim 3,
20 further comprising coding complexity prediction means for predicting coding complexity in each coding system based on the feature of the video picture inside the GOP so as to control a coding quantity at the time of coding in consideration of the complexity.

25 17. A video coding apparatus capable of coding a video picture by either a field structure or a frame structure, the video coding apparatus comprising:

means for discriminating whether each of sequentially input video pictures is an interlaced video picture or a non-interlaced video picture,

the means selecting coding by the field structure if
5 the video picture is an interlaced video picture while the means selecting coding by the frame structure unless the video picture is an interlaced video picture.

18. A video coding apparatus according to claim 17,
wherein in order to discriminate whether the input video
10 picture is an interlaced video picture or a non-interlaced video picture, the spacewise correlation of pixels continuous in a vertical direction at an arbitrary position inside the video picture is measured, so that the video picture is discriminated to be an interlaced video picture
15 if the correlation between the same fields is higher than the correlation between different fields.

19. A video coding apparatus according to claim 18,
wherein the coding by the field structure is selected in the case where the number of pixels satisfying the conditions
20 expressed by inequalities (1) and (2) below exceeds a predetermined rate of the number of pixels satisfying the inequality (1) in measuring the spacewise correlation of the pixels continuous in the vertical direction:

$$\begin{aligned} & \text{Max}(d(0,-2), d(0,2), d(-1,1)) < \text{threshold value} \dots (1) \\ 25 \quad & (\text{Max}(d(0,-2), d(0,2), d(-1,1)) + \text{offset}) < \text{Min}(d(0,-1), d(0,1)) \dots (2) \end{aligned}$$

wherein, a and b represent pixel position in the vertical

direction, $d(a,b)$ represents an absolute difference between
a and b.

20. A video coding apparatus capable of coding a video
picture by either a field structure or a frame structure,
5 the video coding apparatus comprising:

means for calculating the correlation between two video
pictures with a timewise interval with respect to
sequentially input video pictures; and

means for deciding whether the coding is carried out
10 by either a field structure or a frame structure based on
the correlation,

the coding by the frame structure being carried out
in the case of the higher correlation than a predetermined
value while the coding by the field structure being carried
15 out in the case of the lower correlation than it.

21. A video coding apparatus according to claim 20,
wherein the means for calculating the correlation between
the two video pictures comprises:

means for creating a downscaled plane in consideration
20 of features of sequentially input video pictures; and

means for performing simple motion estimation
processing on the downscaled plane, and

wherein the coding by the field structure is selected
in the case where a motion compensatory prediction error
25 obtained by the simple motion estimation processing is larger
than a predetermined value.

22. A video coding apparatus according to claim 21,

wherein the means for creating the downscaled plane in consideration of the feature of the video picture divides the video picture into small blocks and calculates a deviation per divided small block, the deviation being an
5 element of the downscaled plane.

23. A video coding apparatus according to claim 20, further comprising means for discriminating whether the input video picture is an interlaced video picture or a non-interlaced video picture,

10 wherein a video picture variance is analyzed, so that the coding by the field/frame structure is selected by detecting the correlation between the two video pictures with respect to only the video pictures which are discriminated to be interlaced video pictures, while the
15 coding by the frame structure is selected with respect to the video pictures which are not discriminated to be interlaced video pictures.

24. A video coding apparatus according to claim 21, further comprising means for discriminating whether the
20 input video picture is an interlaced video picture or a non-interlaced video picture,

wherein a video picture variance is analyzed, so that the coding by the field/frame structure is selected by detecting the correlation between the two video pictures
25 with respect to only the video pictures which are discriminated to be interlaced video pictures, while the coding by the frame structure is selected with respect to

the video pictures which are not discriminated to be interlaced video pictures.

25. A video coding apparatus according to claim 23, further comprising means for switching and setting the
5 interlaced/non-interlaced video pictures,

wherein it is discriminated whether one video picture input first or a plurality of video pictures are interlaced video pictures or non-interlaced video pictures, so that the means for switching and setting the
10 interlaced/non-interlaced video pictures is set based on the discrimination result.

26. A video coding apparatus according to claim 24, further comprising means for switching and setting the interlaced/non-interlaced video pictures,

15 wherein it is discriminated whether one video picture input first or a plurality of video pictures are interlaced video pictures or non-interlaced video pictures, so that the means for switching and setting the interlaced/non-interlaced video pictures is set based on
20 the discrimination result.

ABSTRACT OF THE DISCLOSURE

A variance between sequential video pictures is extracted, and then, a GOP boundary position is decided based on inter-frame variance information. Furthermore, simple
5 motion estimation is carried out with respect to video pictures inside one GOP. If a motion variation between the video pictures is large, a small predictive frame interval is taken; to the contrary, if the motion variation is small, a large predictive frame interval is taken. The simple
10 motion estimation is carried out between two downscaled feature planes at a timewise fixed interval with respect to a video picture which is discriminated to be an interlaced video picture, wherein a motion compensatory prediction error at that time is output as image variance information.
15 If the image variance is small, coding is conducted by a frame structure; to the contrary, if the image variance is large, the coding is conducted by a field structure. With the above-described processing, it is possible to provide a video coding apparatus for deciding a GOP size and the
20 predictive frame interval according to the feature of the input video picture, and another video coding apparatus for adaptively switching the coding by the frame/field structures according to the feature of the input video picture.

25

Fig. 1

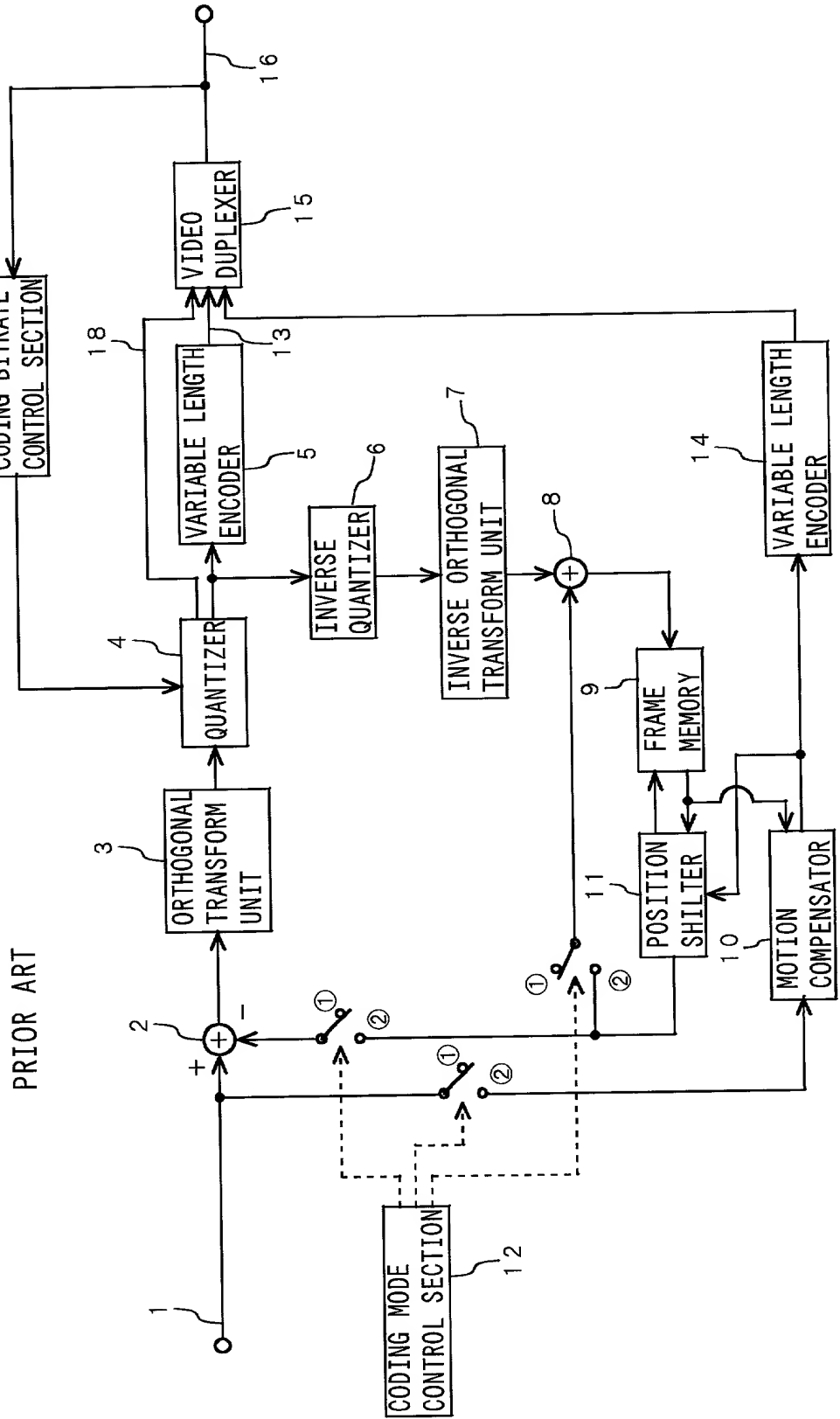


Fig. 2

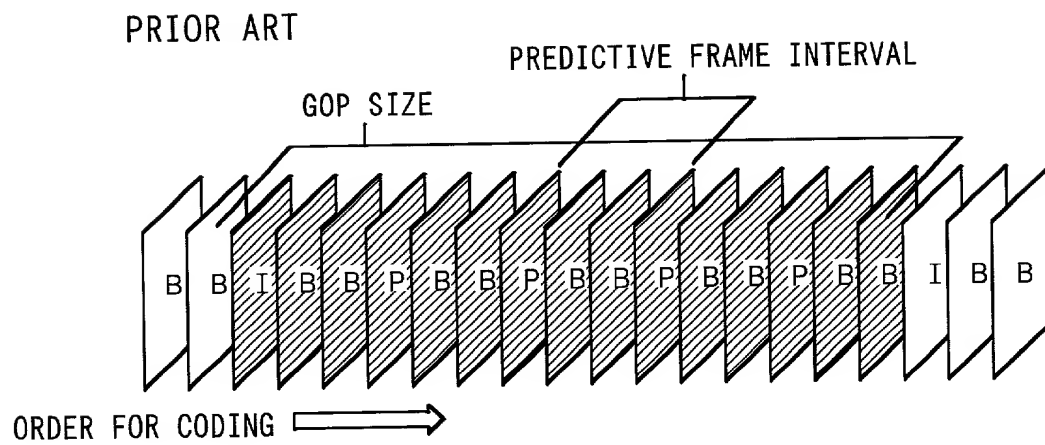


Fig. 5 A

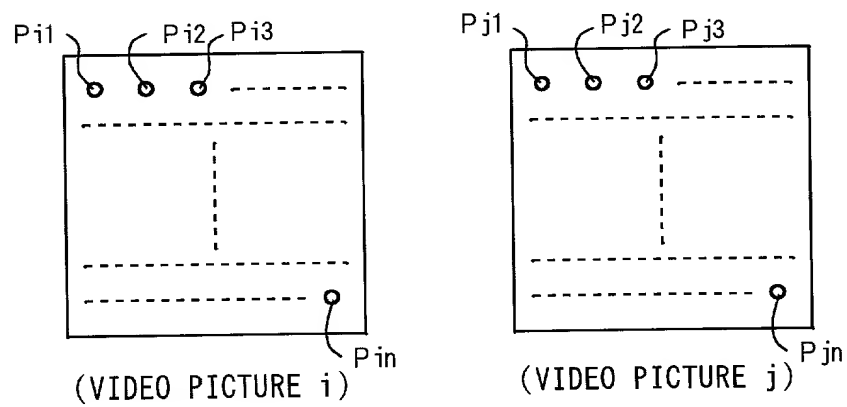


Fig. 5 B

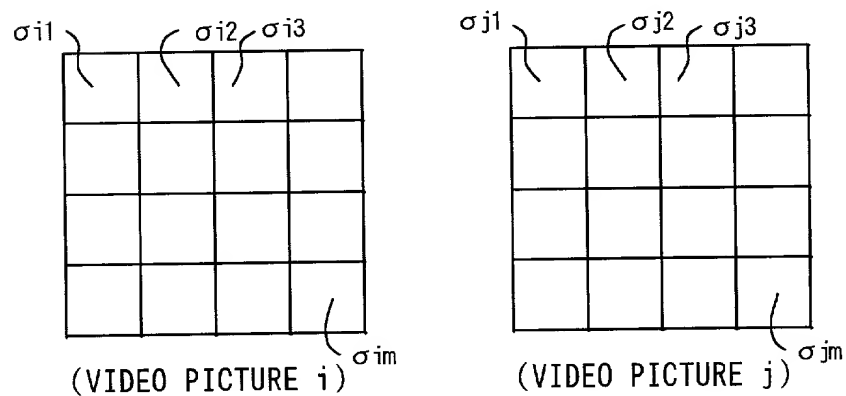
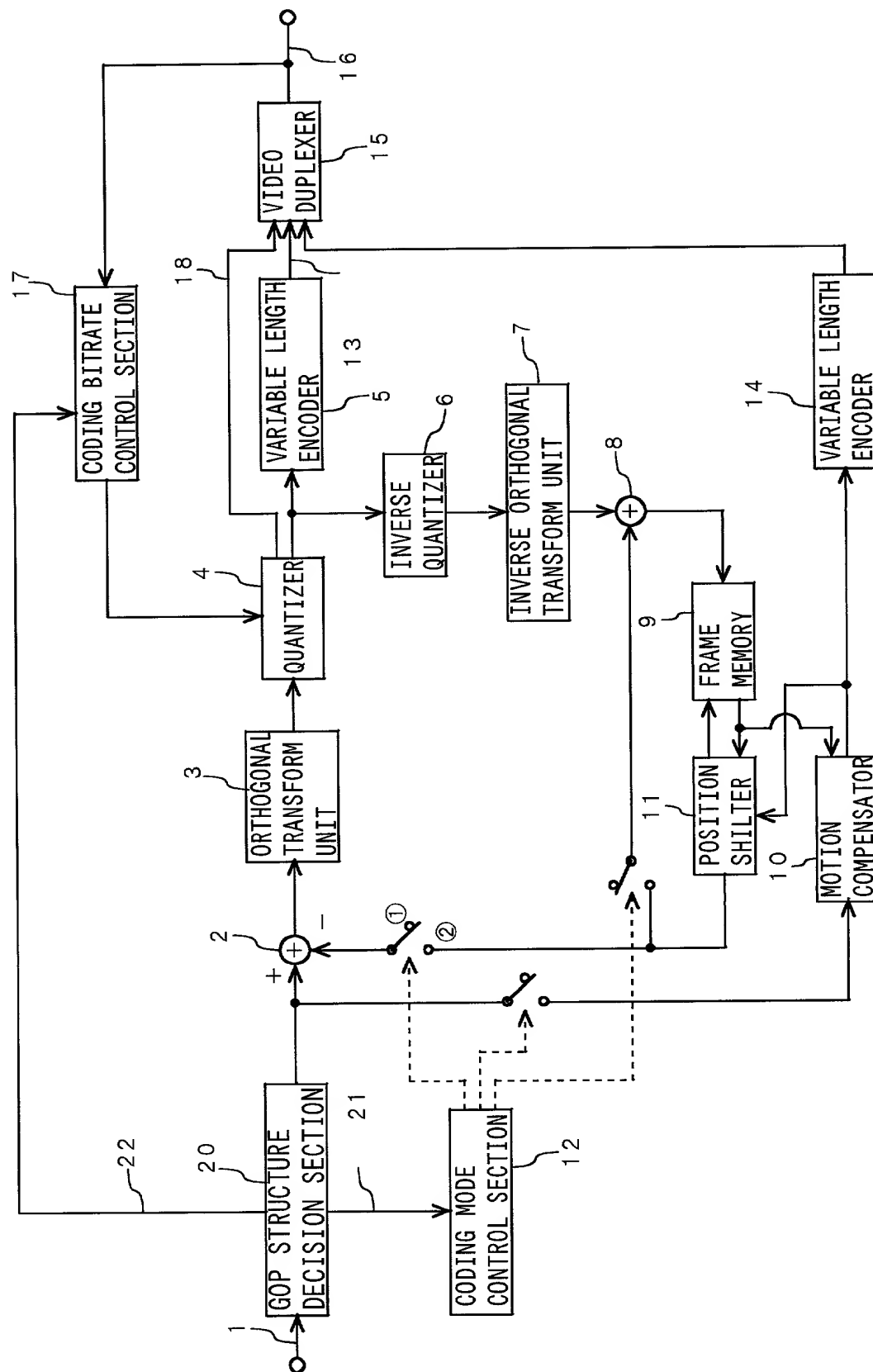
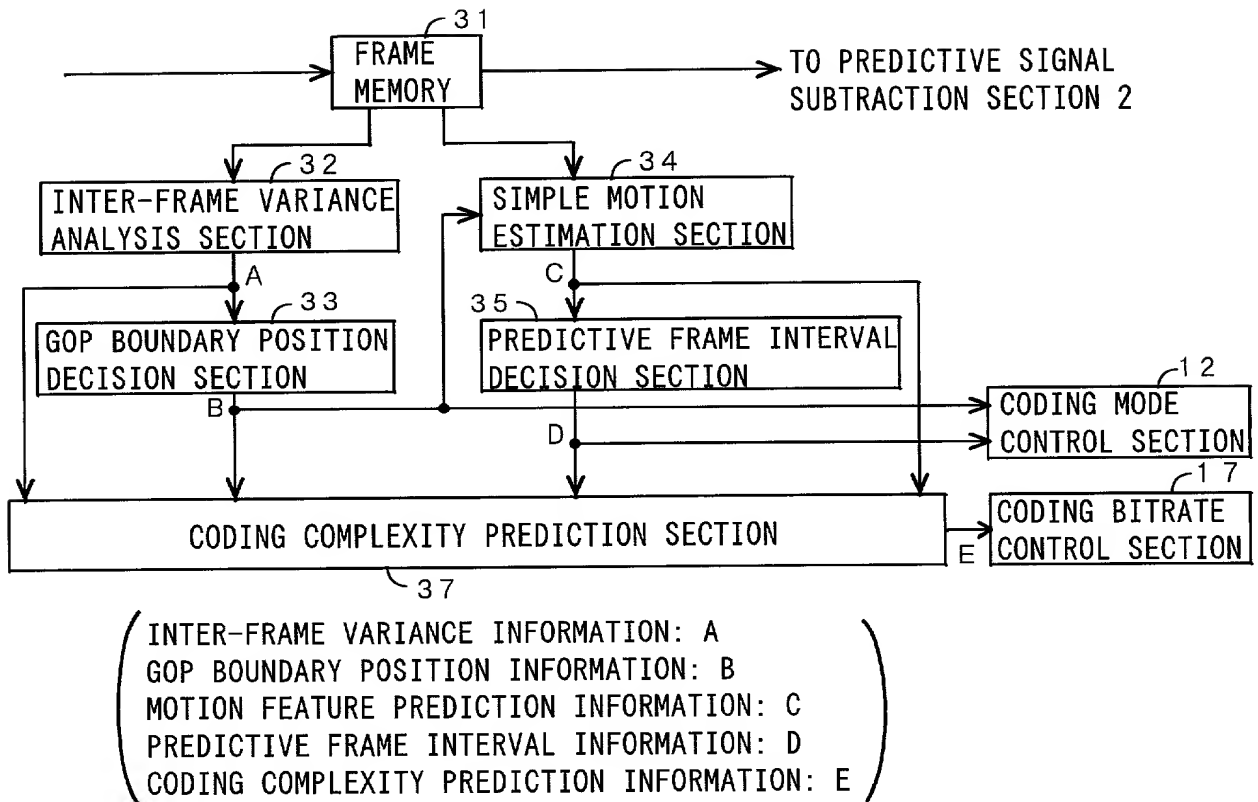


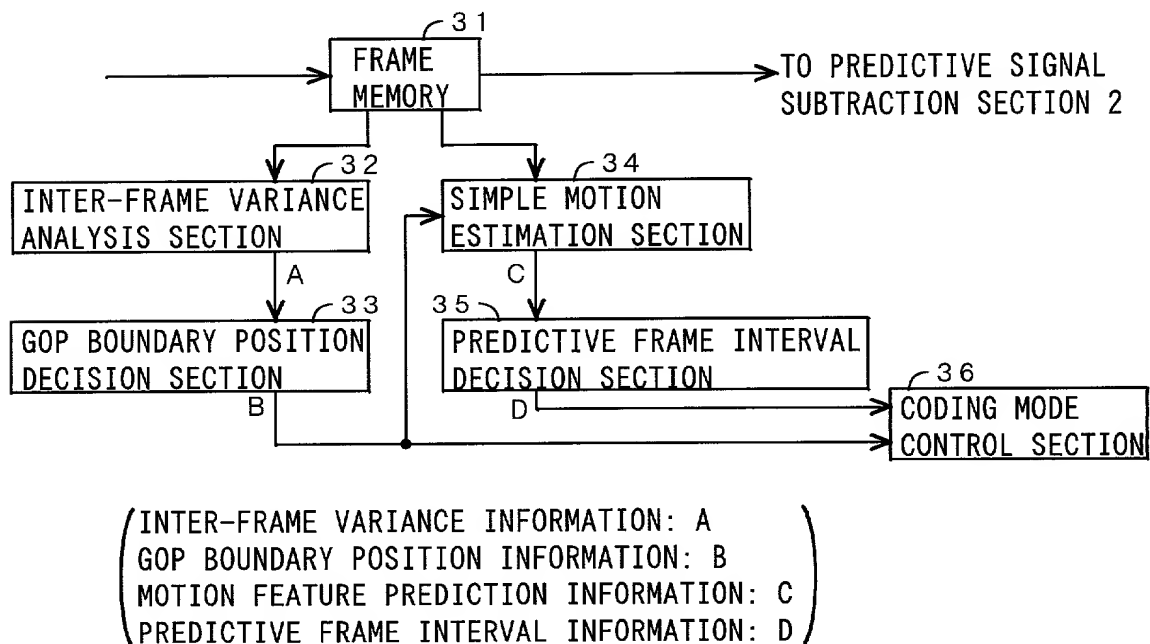
Fig. 3



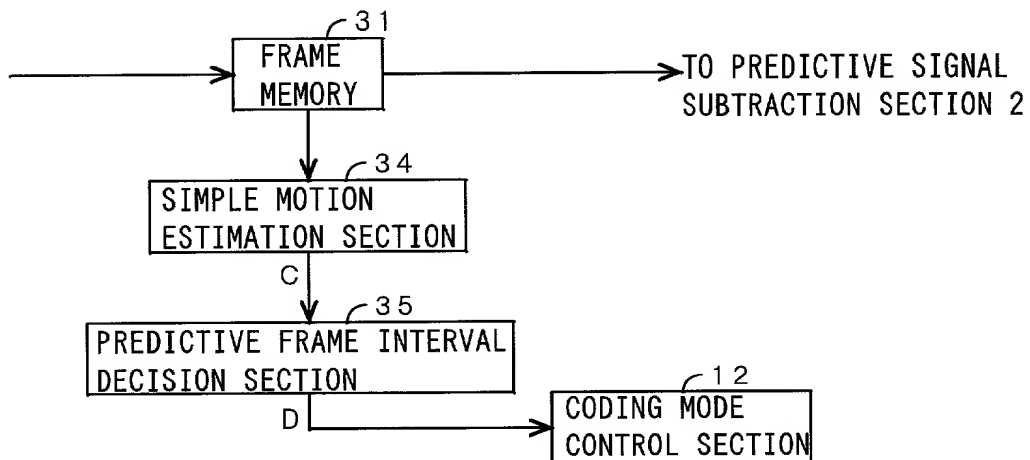
F i g . 4



F i g . 7

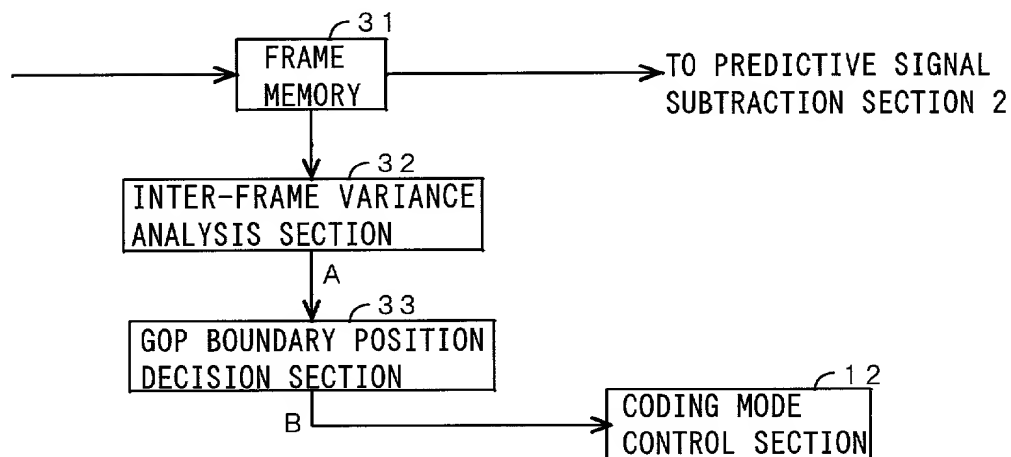


F i g . 8



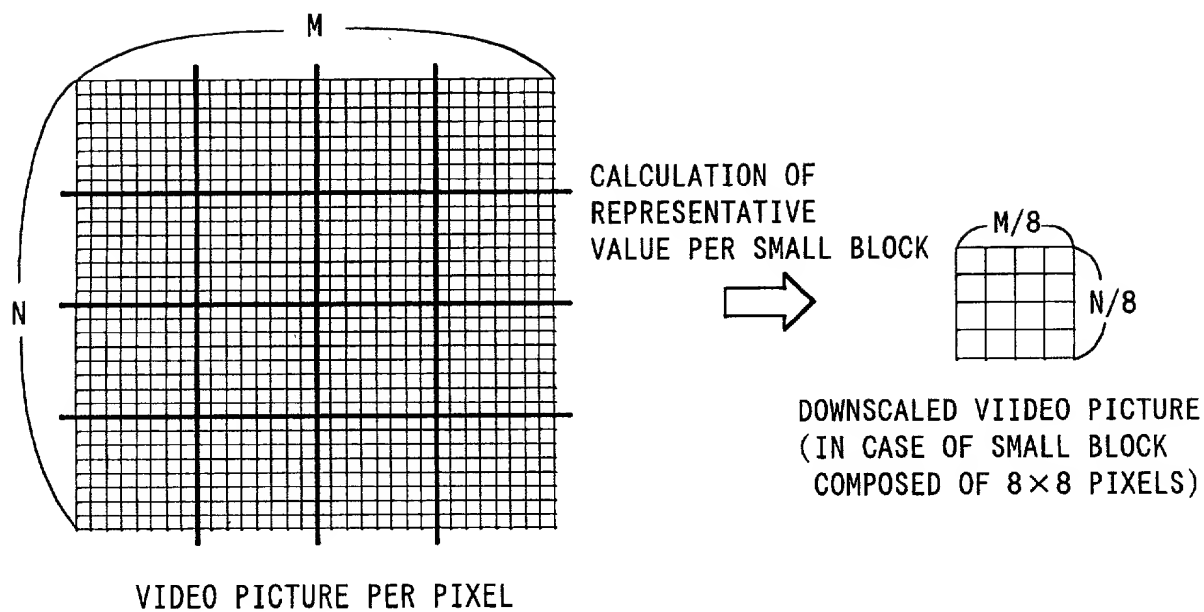
(MOTION FEATURE PREDICTION INFORMATION: C)
 (PREDICTIVE FRAME INTERVAL INFORMATION: D)

F i g . 9

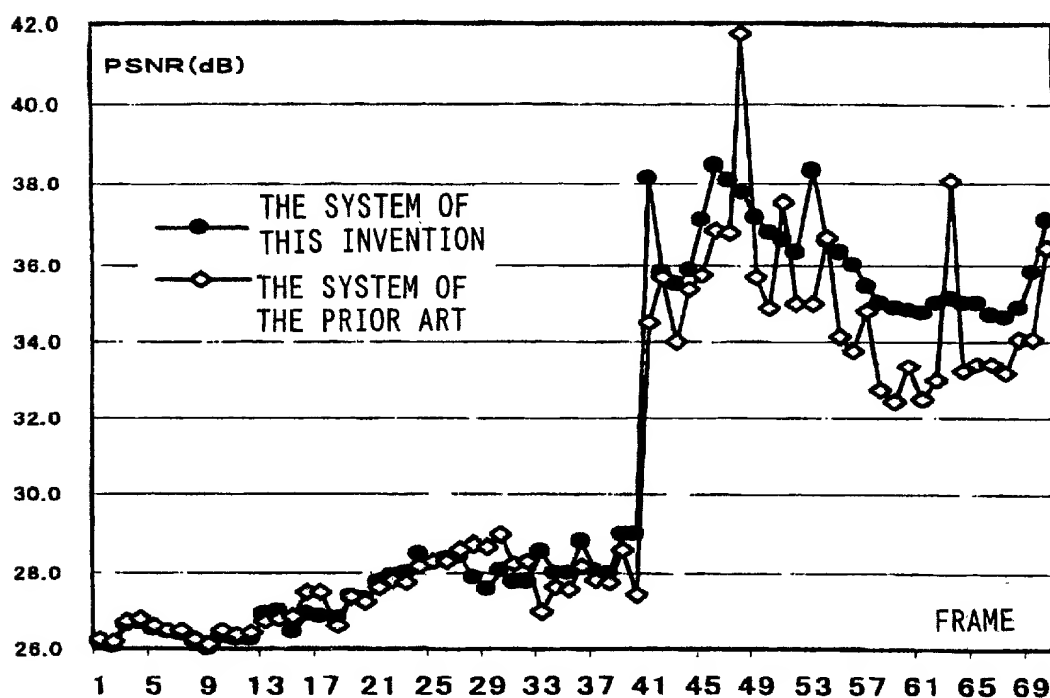


(INTER-FRAME VARIANCE INFORMATION: A)
 (GOP BOUNDARY POSITION INFORMATION: B)

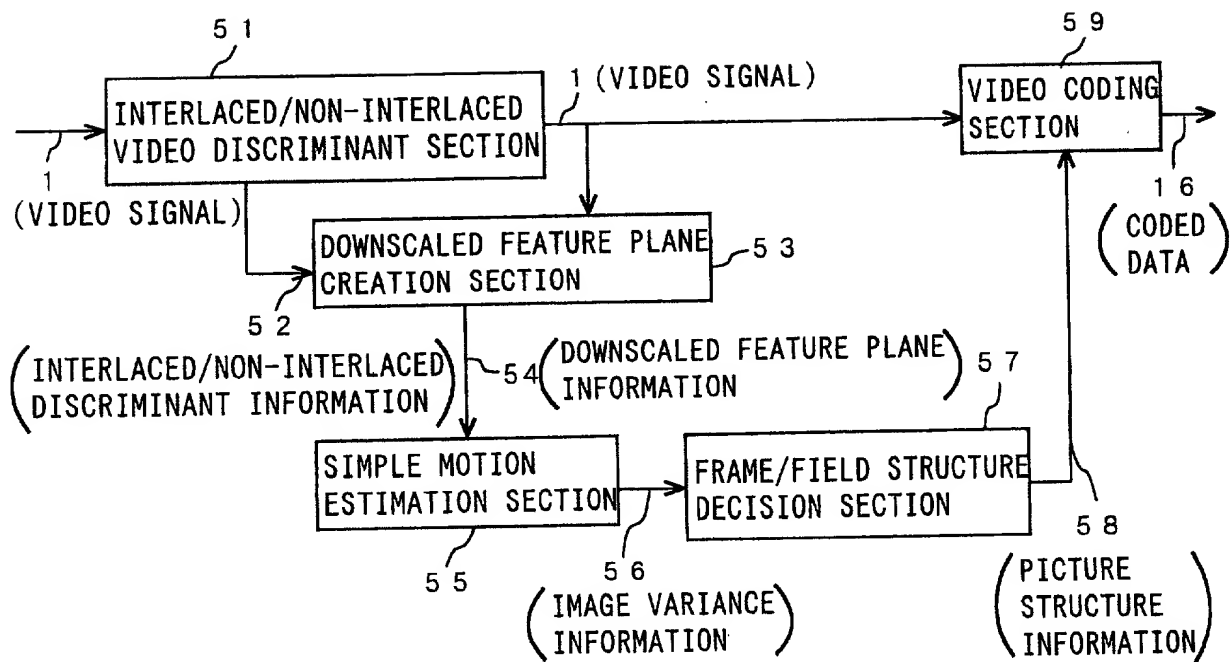
F i g . 6



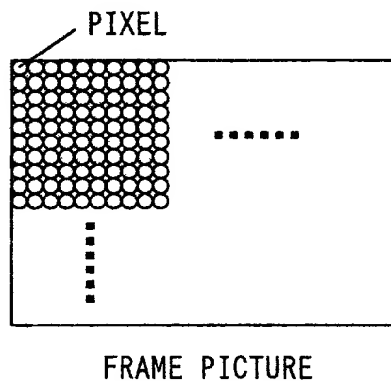
F i g . 1 0



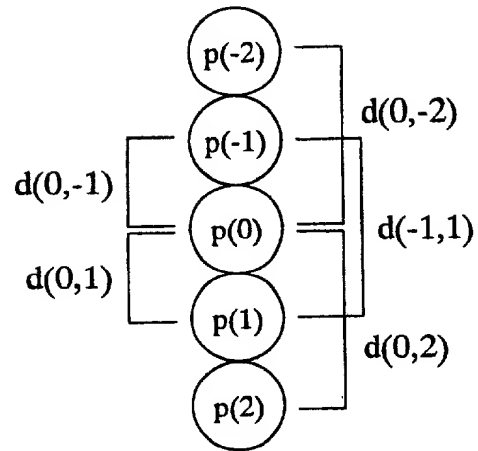
F i g . 1 1



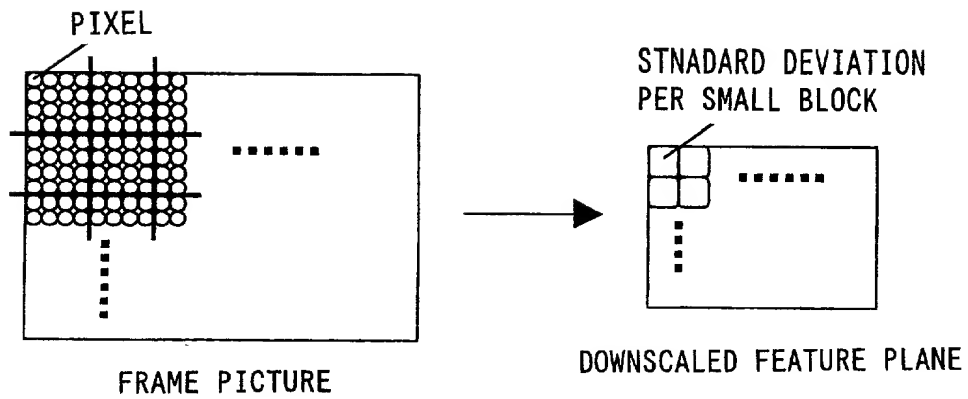
F i g . 1 2



F i g . 1 3



F i g . 1 4



F i g . 1 5

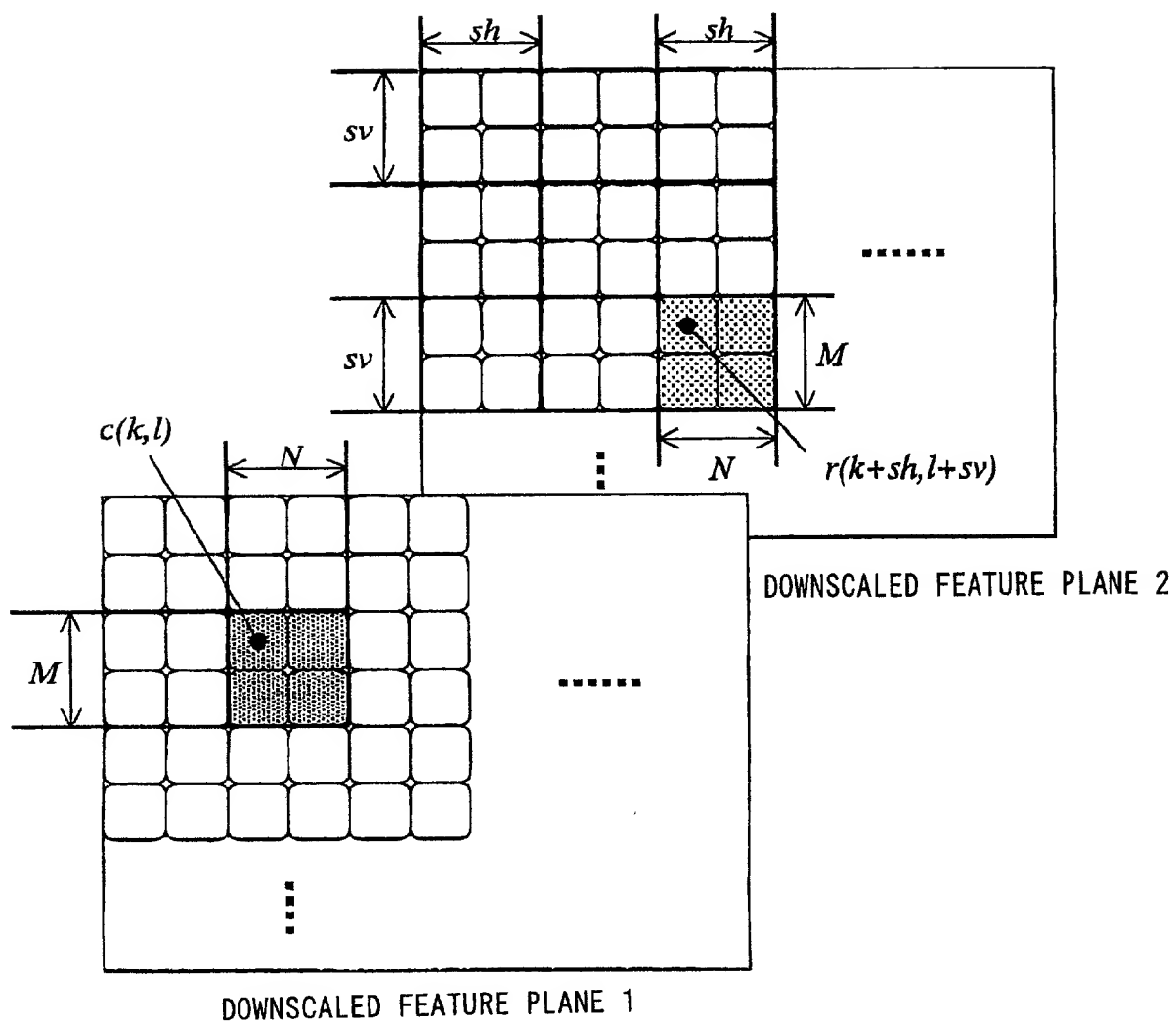


Fig. 16

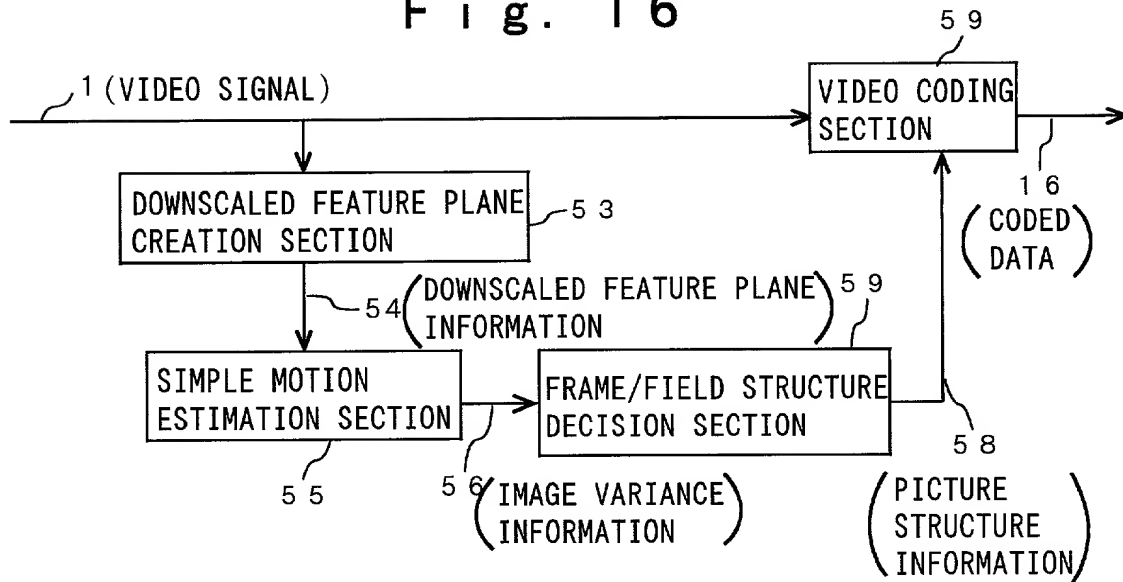


Fig. 17

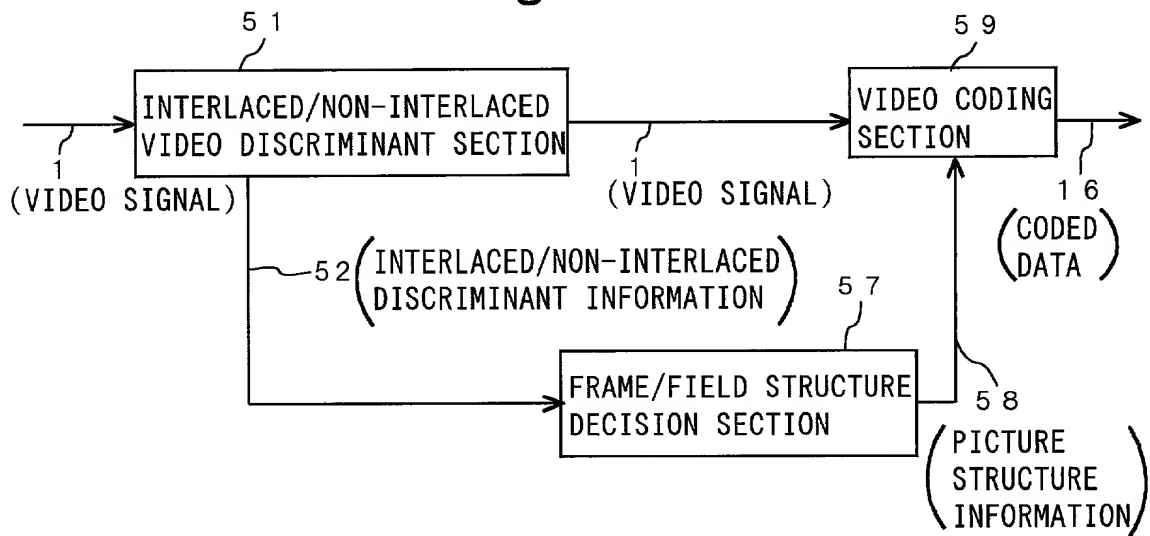


Fig. 18

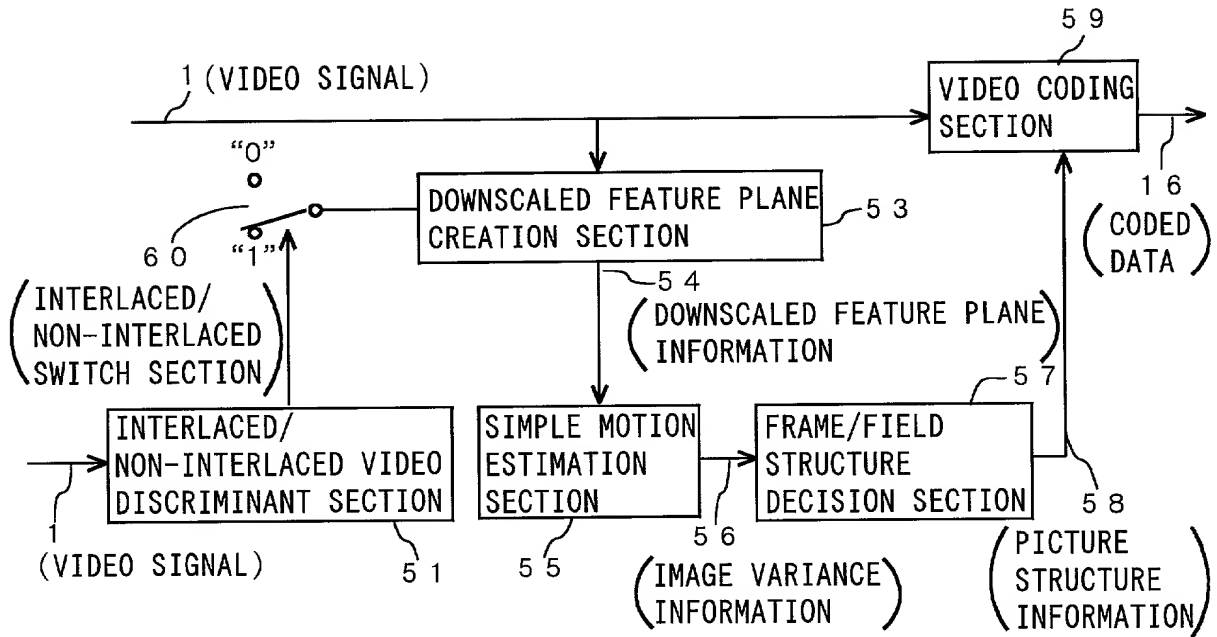
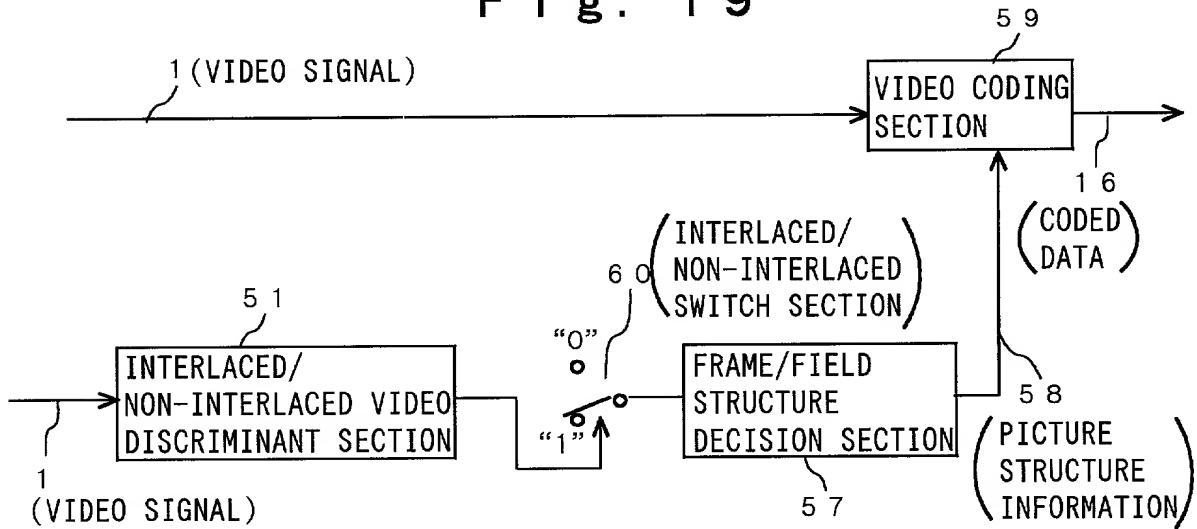


Fig. 19



Declaration For U.S. Patent Application

As a below named inventor, I hereby declare that:

My residence, post office address and citizenship are as stated below next to my name.

I believe I am the original, first and sole inventor (if only one name is listed below) or an original, first and joint inventor (if plural names are listed below) of the subject matter which is claimed and for which a patent is sought on the invention entitled
(Insert Title) A VIDEO CODING APPARATUS ACCORDING TO A FEATURE OF
A VIDEO PICTURE

the specification of which is attached hereto unless the following is checked:



was filed on _____ as United States Application Number or PCT International
Application Number _____ and was amended on _____
(if applicable).

I hereby state that I have reviewed and understand the contents of the above-identified specification, including the claim(s), as amended by any amendment referred to above.

I acknowledge the duty to disclose information which is material to patentability as defined in Title 37, Code of Federal Regulations, § 1.56.

I hereby claim foreign priority benefits under Title 35, United States Code, § 119 (a) - (d) of any foreign application(s) for patent or inventor's certificate listed below and have also identified below any foreign application for patent or inventor's certificate having a filing date before that of the application on which priority is claimed:

(List prior foreign applications. See note A on back of this page)	No. 58046/99	Japan	05/03/1999	Priority Claimed
	(Number)	(Country)	(Day/Month/Year Filed)	<input checked="" type="checkbox"/> Yes <input type="checkbox"/> No
	No. 234538/99	Japan	20/08/1999	<input checked="" type="checkbox"/> Yes <input type="checkbox"/> No
	(Number)	(Country)	(Day/Month/Year Filed)	<input type="checkbox"/> Yes <input type="checkbox"/> No
	(Number)	(Country)	(Day/Month/Year Filed)	<input type="checkbox"/> Yes <input type="checkbox"/> No

(See note B on back of this page)

☐ See attached list for additional prior foreign applications

I hereby claim the benefit under Title 35, United States Code, § 119(e) of any United States provisional application(s) listed below.

_____	_____
(Application Number)	(Filing Date)
_____	_____
(Application Number)	(Filing Date)

I hereby claim the benefit under Title 35, United States Code, § 120 of any United States application(s) listed below and, insofar as the subject matter of each of the claims of this application is not disclosed in the prior United States application in the manner provided by the first paragraph of Title 35, United States Code, § 112, I acknowledge the duty to disclose information which is material to patentability as defined in Title 37, Code of Federal Regulations, § 1.56 which became available between the filing date of the prior application and the national or PCT international filing date of the application:

(List Prior U.S. Applications)	_____	_____	_____
	(Application Serial Number)	(Filing Date)	(Status) (patented, pending, abandoned)
	_____	_____	_____
	(Application Serial Number)	(Filing Date)	(Status) (patented, pending, abandoned)

I hereby appoint the following attorney(s) and/or agent(s) to prosecute this application and to transact all business in the Patent and Trademark Office connected therewith:

James E. Armstrong, III, Reg. No. 18,366; William F. Westerman, Reg. No. 29,988; Ken-Ichi Hattori, Reg. No. 32,861; Le-Nhung McLeland, Reg. No. 31,541; Ronald F. Naughton, Reg. No. 24,616; John R. Pegan, Reg. No. 18,069; William G. Kratz, Jr., Reg. No. 22,631; Albert Tockman, Reg. No. 19,722; Mel R. Quintos, Reg. No. 31,898; Donald W. Hanson, Reg. No. 27,133; Stephen G. Adrian, Reg. No. 32,878; William L. Brooks, Reg. No. 34,129; John F. Carney, Reg. No. 20,276; Edward F. Welsh, Reg. No. 22,455; Patrick D. Muir, Reg. No. 37,403; Gay A. Spahn, Reg. No. 34,978; and John P. Kong, Reg. No. 40,054.

Please direct all communications to the following address:

ARMSTRONG, WESTERMAN, HATTORI,
McLELAND & NAUGHTON
1725 K Street, N.W., Suite 1000
Washington, D.C. 20006
Telephone: (202) 659-2930 Fax: (202) 887-0357

I hereby declare that all statements made herein of my own knowledge are true and that all statements made on information and belief are believed to be true; and further that these statements were made with the knowledge that willful false statements and the like so made are punishable by fine or imprisonment, or both, under Title 18 of the United States Code, § 1001 and that such willful false statements may jeopardize the validity of the application or any patent issued thereon.

Full name of sole or first inventor (given name, family name) Akio YONEYAMA

(See note
C above)

Inventor's Signature Akio Yoneyama Date FEBRUARY 21, 2000

Residence Tokyo, Japan Citizenship Japan

Post Office Address 18-21, Shinmachi 5-chome, Hoya-shi, Tokyo, Japan

Full name of second inventor (given name, family name) Yasuyuki NAKAJIMA

Inventor's Signature Yasuyuki Nakajima Date FEBRUARY 21, 2000

Residence Saitama, Japan Citizenship Japan

Post Office Address 32-24, Shiba-nakata 1-chome, Kawaguchi-shi, Saitama, Japan

Full name of third inventor (given name, family name) Hiromasa YANAGIHARA

Inventor's Signature Hiromasa Yanagihara Date FEBRUARY 21, 2000

Residence Saitama, Japan Citizenship Japan

Post Office Address 41-2-C203, Toro-cho, 1-chome, Omiya-shi, Saitama, Japan

Full name of fourth inventor (given name, family name) Masaru SUGANO

Inventor's Signature Masaru Sugano Date FEBRUARY 21, 2000

Residence Tokyo, Japan Citizenship Japan

Post Office Address 21-2-507, Ichigaya-tamachi 2-chome, Shinjuku-ku, Tokyo, Japan

Full name of fifth inventor (given name, family name) _____

Inventor's Signature _____ Date _____

Residence _____ Citizenship _____

Post Office Address _____

Full name of sixth inventor (given name, family name) _____

Inventor's Signature _____ Date _____

Residence _____ Citizenship _____

Post Office Address _____

Full name of seventh inventor (given name, family name) _____

Inventor's Signature _____ Date _____

Residence _____ Citizenship _____

Post Office Address _____

Full name of eighth inventor (given name, family name) _____

Inventor's Signature _____ Date _____

Residence _____ Citizenship _____

Post Office Address _____